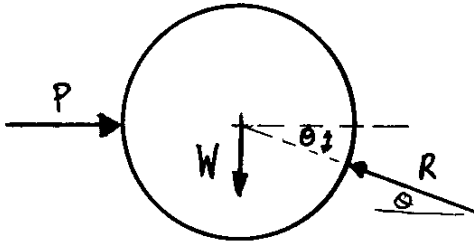


3/21 find P such that cylinder will begin to roll over the step.

FREE BODY DIAGRAM



R is exerted at point of CONTACT AND IS NORMAL TO SURFACE (we are assuming contact is smooth)

Note, no force @ bottom surface because

we assume CYLINDER is ABOUT to roll over obstacle, i.e. beginning to LIFT.

EQUILIB conditions

$$\sum F_x = 0$$

$$P - R \cos \theta = 0$$

$$\text{OR } P - R \left(\frac{\sqrt{2rh - h^2}}{r} \right) = 0 \quad (1)$$

if we look at geometry

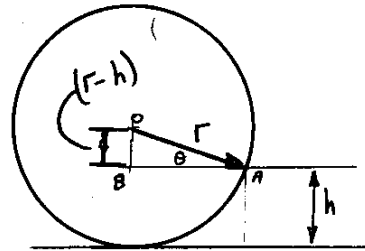


$$\|OB\| = r - h$$

$$\|OA\| = r$$

$$\|BA\| = \sqrt{r^2 - (r-h)^2} = \sqrt{r^2 - r^2 + 2rh - h^2} = \sqrt{2rh - h^2}$$

$$\Rightarrow \cos \theta = \frac{\sqrt{2rh - h^2}}{r} \quad \sin \theta = \frac{r-h}{r}$$



$$\sum F_y = 0 \Rightarrow W - R \sin \theta = 0 \quad \text{or equivalently}$$

$$W - R \left(\frac{r-h}{r} \right) = 0 \quad (2)$$

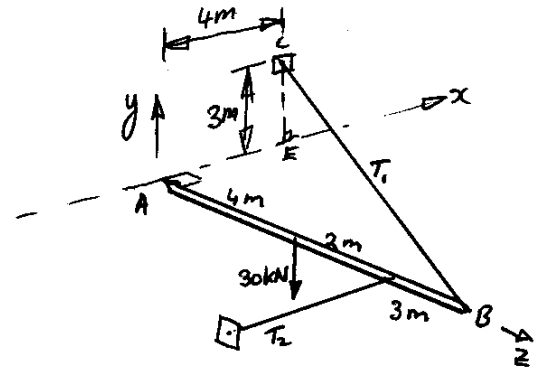
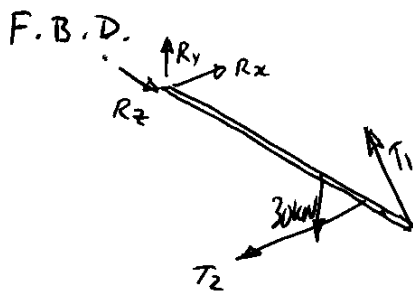
Eliminate R between (1) & (2)

$$W - \left(\frac{r-h}{r} \right) P \left(\frac{r}{\sqrt{2rh - h^2}} \right) = 0 \quad \text{note } W = mg \text{ so}$$

$$mg = P \frac{r-h}{\sqrt{2rh - h^2}} \quad \text{and} \quad \underline{\underline{P = \frac{mg \sqrt{2rh - h^2}}{r-h}}}$$

note $r > h$, as $r \rightarrow h$ $P \rightarrow \infty$... v. hard to push.

if $r < h \Rightarrow$ SQUARE ROOT $\rightarrow$ IMAGINARY; i.e. impossible



TAKE MOMENT ABOUT x axis

$$(30 \text{ kN})(4) - (T_{1y})(9) = 0 \Rightarrow T_{1y} = 13.33 \text{ kN}$$

$\vec{T}_1$ is directed along cord CB $\Rightarrow$ components must correspond to components of $\vec{CB}$

$$\text{i.e. } T_{1x} = \left(\frac{T_{1y}}{3}\right)(4) = \left(\frac{13.33}{3}\right)(4) = 17.77 \text{ kN}$$

$$T_{1z} = -\left(\frac{T_{1y}}{3}\right)(9) = -\left(\frac{13.33}{3}\right)(9) = -39.99 \text{ kN}$$

$$\therefore \vec{T}_1 = 17.77\hat{i} + 13.33\hat{j} - 39.99\hat{k} \quad \text{kN}$$

$$\& \|\vec{T}_1\| = 45.75 \text{ kN}$$

TAKE MOMENTS ABOUT y axis and apply Equilib condition

$$(T_{1x})(9) - (T_2)(6) = 0 \Rightarrow T_2 = \frac{(T_{1x})(9)}{6} = \frac{(17.77)(9)}{6}$$

$$\|\vec{T}_2\| = 26.655 \text{ kN} \& \vec{T}_2 = -26.655\hat{i} \quad (\text{kN}).$$

Finally use two force ~~moment~~^{EQUILIB} equations to get R_x & R_y & R_z at A

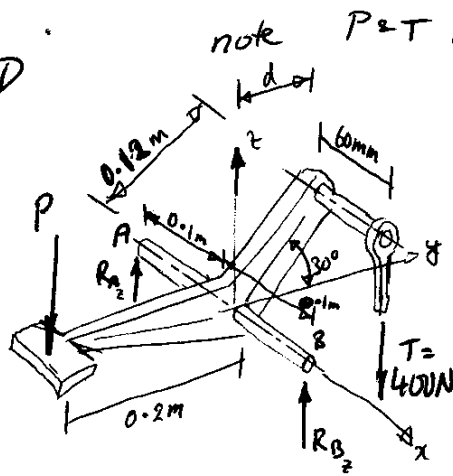
$$\sum F_z = 0 \quad R_z\hat{k} - 39.99\hat{k} = \vec{0} \Rightarrow R_z = 39.99 \text{ kN}$$

$$\sum F_x = 0 \quad R_x\hat{i} + 17.77\hat{i} - 26.655\hat{i} = \vec{0} \Rightarrow R_x = 8.89 \text{ kN}$$

$$\sum F_y = 0 \quad R_y\hat{j} - 30\hat{j} + 13.33\hat{j} = \vec{0} \Rightarrow R_y = 16.67 \text{ kN}$$

$$\|\vec{R}\| = \sqrt{39.99^2 + 8.89^2 + 16.67^2} = \underline{\underline{44.23 \text{ kN}}}$$

F.B.D



$$\text{distance } d = (120) \cos(30^\circ) = \underline{60\sqrt{3}}$$

take moments about x axis and apply Equilib $\Sigma M = 0$
(Note that A-B is a BEARING).

$$(P)(0.2) - (400)(0.12 \cos 30^\circ) = 0$$

$$\Rightarrow P = 207.85 \text{ kN} \quad (\text{DOWN, AS SHOWN}).$$

$$R_{Az} + R_{Bz} - P - T = 0$$

$$\Rightarrow R_{Az} + R_{Bz} = 400 + 207.85 = 607.85$$

Take moments about y-axis and apply Equilib

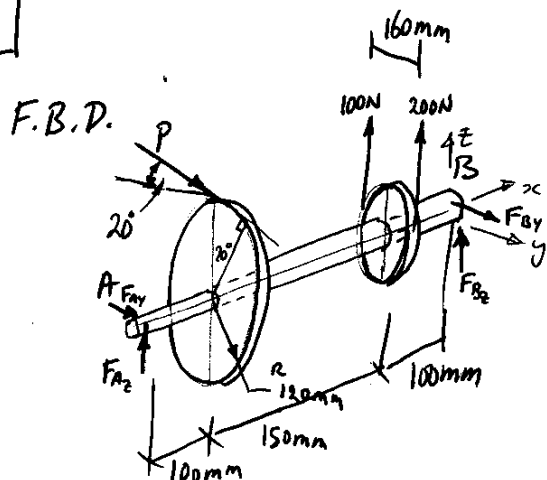
$$+(T)(0.06) - (R_{Bz})(0.1) + (R_{Az})(0.1) = 0$$

$$R_{Az} - R_{Bz} = \frac{-(400)(0.06)}{0.1} = -240$$

We have two equations

$$\begin{aligned} R_{Az} - R_{Bz} &= -240 \\ R_{Az} + R_{Bz} &= 607.85 \end{aligned} \Rightarrow R_{Az} = \left(\frac{607.85 - 240}{2} \right) = \underline{\underline{183.925 \text{ N}}}$$

$$R_{Bz} = (607.85 - 183.925) = \underline{\underline{423.925 \text{ N}}}$$



find gear tooth force P and reactions supported at A and B

To find P , take moments about shaft and apply equilibrium assuming no friction in shaft bearings

$$-(200)(80) + (100)(80) + (P)(120)(\cos 20^\circ) = 0 \quad \text{Nmm}$$

$$\Rightarrow P = \frac{(80)(100)}{(120)(\cos 20^\circ)} = \underline{\underline{70.945 \text{ N}}}$$

$$\sum F_y = 0 \quad F_{By} + F_{Ay} + P \cos(20^\circ) = 0 \quad (1)$$

$$\sum F_z = 0 \quad F_{Bz} + F_{Az} - P \sin(20^\circ) + 300 \text{ N} = 0 \quad (2)$$

Take moments about a vertical axis thru A

$$-P \cos(20^\circ)(100) - F_{By}(350) = 0 \quad F_{By} = -\frac{(70.945)(\cos 20^\circ)(100)}{(350)} = -19.05 \text{ N}$$

Take moments about a horizontal axis thru A

$$-P(\sin 20^\circ)(100) + (300)(250) + (F_{Bz})(350) = 0$$

$$F_{Bz} = \frac{(70.945)(\sin 20^\circ)(100) - (300)(250)}{(350)} = -207.35 \text{ N}$$

$$\therefore \|F_B\| = \sqrt{207.35^2 + 19.05^2} = \underline{\underline{208.2 \text{ N}}}$$

Return to (1) & (2)

$$F_{Ay} = -P(\cos 20^\circ) - F_{By} = -47.6 \text{ N}$$

$$F_{Az} = P(\sin 20^\circ) - 300 - F_{Bz} = -68.4 \text{ N}$$

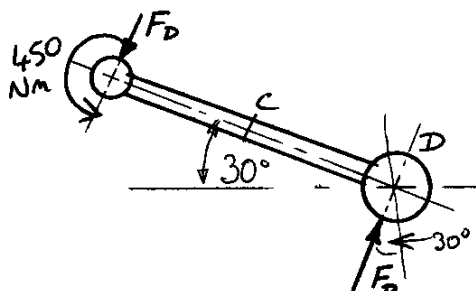
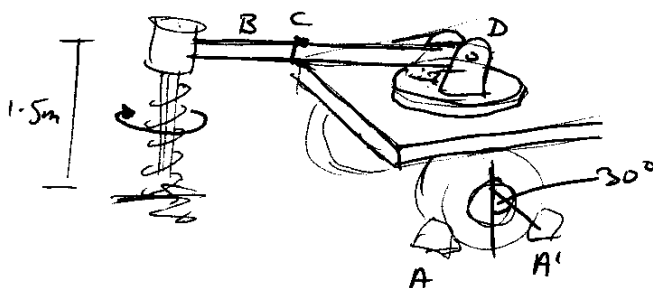
$$\|F_A\| = \sqrt{47.6^2 + 68.4^2} = \underline{\underline{83.3 \text{ N}}}$$

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14

first, assume rotation shown in figure is the direction of torque applied to the auger. the torque exerted on the motor will be equal and opposite.

take the offered hint and look on problem from above, DRAW F.B.D for arm



NOTE: free rotation at D
 $\Rightarrow$ NO moment applied here
 free slide at C
 $\Rightarrow$ no force parallel to arm

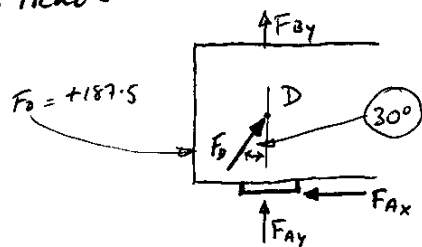
Apply Equilib

$$\Rightarrow \sum M_i = 0 \quad (F_D)(2.4) + M = 0$$

$$\Rightarrow F_D = \frac{-M}{2.4} = \frac{-450}{2.4} = -187.5$$

minus sign $\Rightarrow$ F is opposite dirxn to that shown.

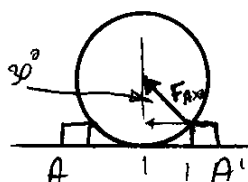
Now track



ONLY need x dirxn

$$\Rightarrow F_{Ax} = F_D \sin(30^\circ) = (187.5)(\sin 30^\circ)$$

Now look at wheel



if H_z component is $(187.5)(\sin 30^\circ)$

$\Rightarrow$ Radial component is

$$\underline{\underline{187.5 \text{ N}}}$$

at A'

A does not
mass = 45 kg.

Note we did not find forces in hinges A & B. We did not need to do so is a longer undertaking.