

Last Lecture:

LAST = Previous

E1

INTRODUCED PLANE KINETICS OF RIGID BODIES

$$\underline{\sum \vec{F} = m \vec{a}_G}$$

$$\underline{\sum \vec{M}_G = \dot{H}_G = \alpha I_G}$$

(FOR 2-D CASE)

⊗ $I_G = \int r^2 dm$ moment of inertia
 $= \rho \int r^2 dV$ if ρ is constant throughout volume

Parallel axis theorem: $I = I_G + md^2$

Radius of Gyration: $k = \sqrt{\frac{I}{m}} \Leftrightarrow I = k^2 m$

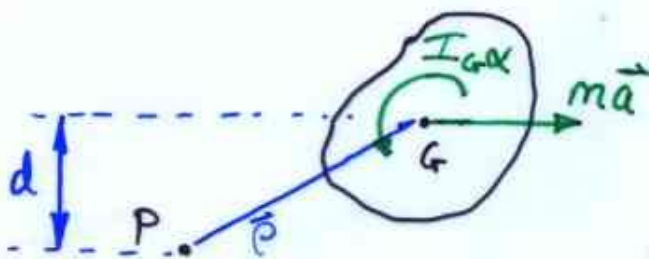
Consider alternative forms of moment eqn..

$$\sum \vec{M}_P = \dot{H}_G + \vec{r} \times m \vec{a}_G \quad \vec{r} \text{ is vector } \vec{PG}$$

or 2D:

$$\sum M_P = I_G \alpha \pm m a_G d$$

$d = \perp$ dist between
P & vector of accel
sign depends on
right hand rule.



Here $\sum M_P = +I_G \alpha - m a d$ NOTE sign

P is a nonaccelerating point