

2D problem ... So:

$$\vec{r}_i = x_i \hat{i} + y_i \hat{j} \quad \vec{a}_P = a_{Px} \hat{i} + a_{Py} \hat{j}$$

$$\vec{\alpha} = \alpha \hat{k} \quad \text{and} \quad \vec{M}_{Pi} = M_{Pi} \hat{k}$$

$$\text{So } M_{Pi} \hat{k} = m_i \left\{ (x_i \hat{i} + y_i \hat{j}) \times [a_{Px} \hat{i} + a_{Py} \hat{j}] + (x_i \hat{i} + y_i \hat{j}) \times [\alpha \hat{k} \times (x_i \hat{i} + y_i \hat{j})] \right\}$$

$$M_{Pi} \hat{k} = m_i \left\{ -y_i a_{Px} + x_i a_{Py} + \alpha (x_i^2 + y_i^2) \right\} \hat{k}$$

note  $x^2 + y^2 = r^2$

if we let  $m_i \rightarrow dm$  & integrate over mass  $m$  we get ...

$$\sum M_P = - \left( \int_m y dm \right) a_{Px} + \left( \int_m x dm \right) a_{Py} + \left( \int_m r^2 dm \right) \alpha$$

<p style="text-align: center;">↓</p> <p>moment of external forces about Point P (internal moments cancel out)</p>	<p style="text-align: center;">↓</p> <p><math>m y_G</math> i.e. the integrals locate centre of mass</p>	<p style="text-align: center;">↓</p> <p><math>m x_G</math></p>	<p style="text-align: center;">↓</p> <p>M.O. Inertia about P <math>I_P</math></p>
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$$\boxed{\sum M_P = m \vec{p} \times \vec{a}_P + I_P \alpha}$$

$$\boxed{\vec{p} = x_G \hat{i} + y_G \hat{j}}$$

Say  $P = G$  (center of mass)

$$\Rightarrow \underline{\underline{\sum M_G = m \vec{0} \times \vec{a}_G + I_G \alpha = I_G \alpha}}$$

OR Say P has no accel'n

$$\Rightarrow \sum M_P = m \vec{p} \times \vec{0} + I_P \alpha$$

$$\underline{\underline{\sum M_P = I_P \alpha}}$$